

# Integrability of certain restricted systems of material points

Andrzej J. Maciejewski

Institute of Astronomy, University of Zielona Góra, Poland

Dynamics in Syberia  
February 29 – March 4,  
Novosibirsk, 2016

# Outline

---

# Outline

---

- 1 Open chains dynamics
- 2 Constrained systems on a sphere (not finished)
- 3 Anisotropic Kepler problem

# Open $n$ -chain

- $(n + 1)$  points  $(m_i, \mathbf{q}_i)$ ,  $i = 0, \dots, n$ ,
- $n$  holonomic constraints:

$$\|\mathbf{q}_i - \mathbf{q}_{i-1}\| = l_i > 0, \quad \text{for } i = 1, \dots, n.$$

- configuration space:

$$(\mathbf{r}, \mathbf{e}_1, \dots, \mathbf{e}_n) \in \mathbb{R}^d \times \mathbb{S}^{d-1} \times \dots \times \mathbb{S}^{d-1}$$

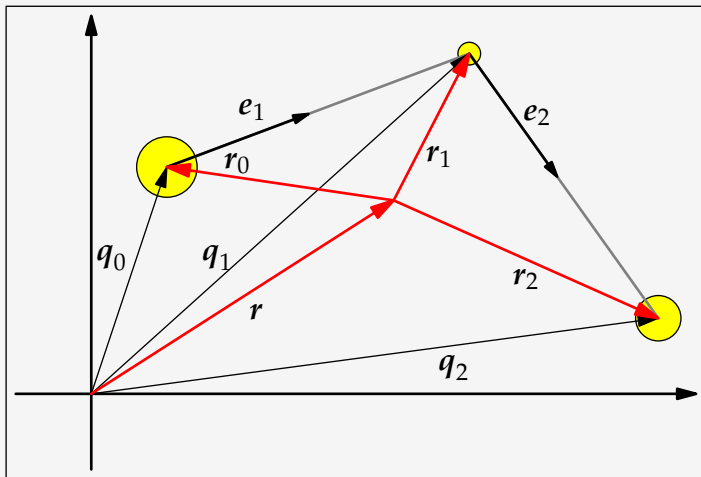
where

$$\mathbf{r} = \frac{1}{m} \sum_{i=0}^n m_i \mathbf{q}_i, \quad \text{where } m = \sum_{i=0}^n m_i.$$

end

$$\mathbf{e}_i = \frac{1}{l_i} (\mathbf{q}_i - \mathbf{q}_{i-1}), \quad \text{for } i = 1, \dots, n,$$

- number of degrees of freedom:  $d + n(d - 1)$

A 2-chain in  $\mathbb{R}^2$ 

# Lagrange function

Kinetic energy

$$T = \frac{1}{2}m\|\dot{\mathbf{r}}\|^2 + \frac{1}{2} \sum_{\alpha,\beta=1}^n I_{\alpha,\beta} \dot{\mathbf{e}}_{\alpha} \cdot \dot{\mathbf{e}}_{\beta}.$$

where

$$I_{\alpha,\beta} := l_{\alpha}l_{\beta} \left( \sigma_{\gamma} - \frac{\sigma_{\alpha}\sigma_{\beta}}{m} \right) \quad \text{with} \quad \gamma = \max(\alpha, \beta).$$

and

$$\sigma_{\alpha} := \sum_{k=\alpha}^n m_k.$$

# Example: $n$ -chain in constant gravity field

$$V = -g \sum_{i=0}^n m_i \mathbf{n} \cdot \mathbf{q}_i = -g \sum_{i=0}^n m_i \mathbf{n} \cdot (\mathbf{r} + \mathbf{r}_i) = -mg \mathbf{n} \cdot \mathbf{r}$$

Equations of motion:

$$m\ddot{\mathbf{r}} = -mg\mathbf{n},$$

and

$$\sum_{\beta=1}^n I_{\alpha,\beta} \ddot{\mathbf{e}}_{\beta} + \frac{\partial V}{\partial \mathbf{e}_{\alpha}} = \lambda_{\alpha} \mathbf{e}_{\alpha}, \quad \alpha = 1, \dots, n,$$

# Integrability of free $n$ -chain

- 1 For a free  $n$ -chain  $r$  is cyclic.
- 2 Reduced system has  $n \cdot (d - 1)$  degrees of freedom.
- 3 Reduced system has  $\text{SO}(d, \mathbb{R})$  symmetry group.

The simplest case: planar  $n$ -chain

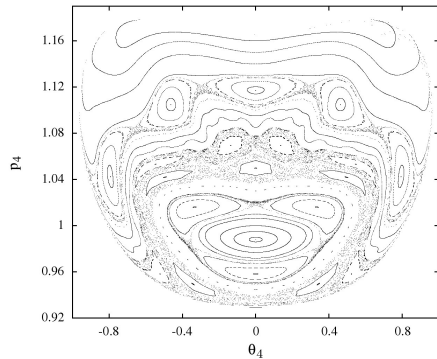
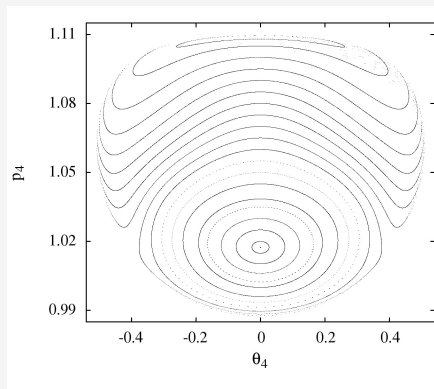
## Conjecture

*Arbitrary planar  $n$ -chain with  $n \geq 3$  is not integrable.*

Problem: number of parameters:  $n(n + 1)/2$ .



# Examples



# $n$ -chain in a circular orbit

Lagrange function

$$L = \frac{1}{2} \sum_{\alpha, \beta=1}^n I_{\alpha, \beta} (\dot{\mathbf{s}}_{\alpha} + \boldsymbol{\omega} \times \mathbf{s}_{\alpha}) \cdot (\dot{\mathbf{s}}_{\beta} + \boldsymbol{\omega} \times \mathbf{s}_{\beta}) - V,$$

where

$$V = -\frac{1}{2} \omega^2 \sum_{\alpha, \beta=1}^n I_{\alpha, \beta} [3(\mathbf{s} \cdot \mathbf{s}_{\alpha})(\mathbf{s} \cdot \mathbf{s}_{\beta}) - \mathbf{s}_{\alpha} \cdot \mathbf{s}_{\beta}],$$

# Planar 2-chain in orbit

Coordinates  $(\varphi_1, \varphi_2)$ :

$$\mathbf{s}_1 = (\cos \varphi_1, \sin \varphi_1, 0)^T, \quad \mathbf{s}_2 = (\cos \varphi_2, \sin \varphi_2, 0)^T.$$

$$L = \frac{1}{2} \left[ I_{1,1} (\dot{\varphi}_1 + 1)^2 + I_{2,2} (\dot{\varphi}_2 + 1)^2 \right] + \\ I_{1,2} \cos(\varphi_1 - \varphi_2) (\dot{\varphi}_1 + 1) (\dot{\varphi}_2 + 1) - V(\varphi_1, \varphi_2),$$

where

$$V(\varphi_1, \varphi_2) = -\frac{1}{2} \sum_{\alpha, \beta=1}^2 I_{\alpha, \beta} \left[ 3 \cos \varphi_\alpha \cos \varphi_\beta - \cos(\varphi_\alpha - \varphi_\beta) \right].$$

# Planar 2-chain in orbit

Parameters:

$$I_{1,1} = \frac{m_0(m_1 + m_2)l_1^2}{m_0 + m_1 + m_2}, \quad I_{2,2} = \frac{m_2(m_0 + m_1)l_2^2}{m_0 + m_1 + m_2},$$

$$I_{1,2} = \frac{m_0 m_2 l_1 l_2}{m_0 + m_1 + m_2},$$

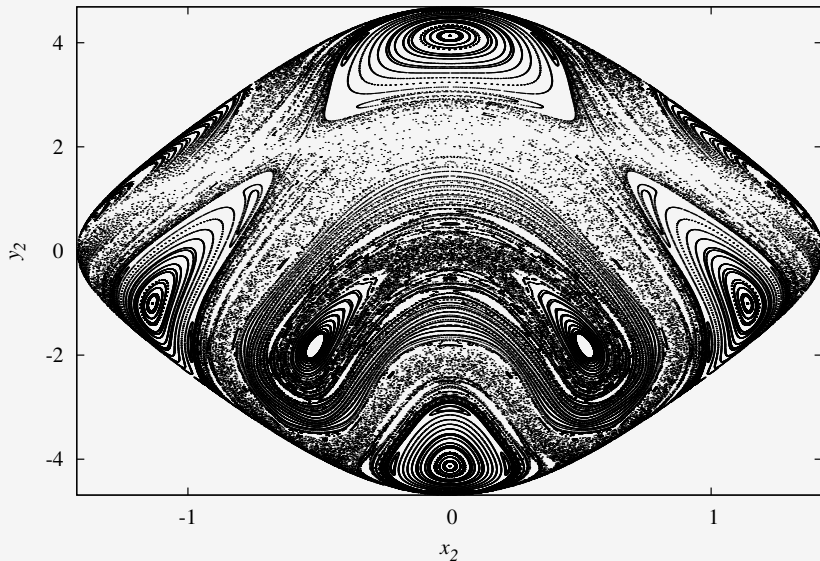
$$\lambda_1 = \frac{I_{1,1}}{I_{1,2}}, \quad \lambda_2 = \frac{I_{2,2}}{I_{1,2}}, \quad \lambda = \lambda_1 + \lambda_2,$$

# Planar 2-chain in orbit

Non-canonical variables  $(x_1, x_2) := (\varphi_1, \varphi_2 - \varphi_2)$ ,  
 $(y_1, y_2) := (\dot{x}_1, \dot{x}_2)$ . Energy integral

$$H = \frac{1}{2} \left[ (\lambda + 2 \cos x_2) y_1^2 + 2 y_1 y_2 (\lambda_2 + \cos x_2) + \lambda_2 y_2^2 \right] - \frac{3}{4} [\lambda + \lambda_1 \cos(2x_1) + \lambda_2 \cos(2(x_1 + x_2)) + 2 \cos x_2 + 2 \cos(2x_1 + x_2)]$$

# Planar 2-chain in orbit



# Main result

## Theorem

*The system does not admit an additional meromorphic first integral.*

Main tool: differential Galois theory.

## Theorem (Morales-Ramis)

*If a Hamiltonian system is integrable in the Liouville sense with meromorphic first integrals, then the differential Galois group of variational equations along a particular solution is virtually Abelian.*

- Morales Ruiz, J. J., *Differential Galois theory and non-integrability of Hamiltonian systems*, volume 179 of *Progress in Mathematics*, Birkhäuser Verlag, Basel, 1999.
- Audin, M., *Les systèmes hamiltoniens et leur intégrabilité*, Cours Spécialisés 8, Collection SMF, SMF et EDP Sciences, Paris, 2001.



# Morales-Ramis theorem for Hamiltonian systems

Hamiltonian system

$$\dot{z} = JH'(z), \quad J = \begin{bmatrix} \mathbf{0} & E_n \\ -E_n & \mathbf{0} \end{bmatrix}, \quad z = [q, p]^T \in \mathbb{C}^{2n}$$

$H(z)$  – a holomorphic function

VE along a particular solution  $\varphi(t)$

$$\dot{y} = JH''(\varphi(t))y.$$

The differential Galois group of VEs is a subgroup of  $\mathrm{Sp}(2n, \mathbb{C})$ .

# Particular solutions

Two invariant planes

$$\mathcal{N}_k = \left\{ (x_1, x_2, y_1, y_2) \in \mathbb{C}^4 \mid x_2 = (k-1)\pi, \quad y_2 = 0 \right\},$$

where  $k = 1, 2$ . The system restriction to  $\mathcal{N}_k$  reads

$$\dot{x} = y, \quad \dot{y} = -\frac{3}{2} \sin(2x), \quad (x, y) = (x_1, y_1).$$

These equations have the energy integral

$$h = \frac{y^2}{2} - \frac{3}{4} \cos(2x).$$

Phase curve  $\Gamma(\eta)$  corresponding to level  $h(x, y) = \eta$ , and  $\Gamma_k(\eta) \subset \mathcal{N}_k$ ,

# Variational equations

$$\ddot{X} - b_k(x, y)X = 0, \quad (x, y) \in \Gamma_k(\eta), \quad k = 1, 2.$$

where:

$$b_k(x, y) = c_k (3 + 2y(2 + y)) + 3(c_k - 1) \cos(2x),$$

and

$$c_k = \frac{\varepsilon_k \lambda - 2}{2(\lambda_1 \lambda_2 - 1)}, \quad \varepsilon_k = (-1)^k,$$

# Variational equations

Change of dependent variables:

$$t \longmapsto z = \frac{1}{\sqrt{3}}y(t)$$

$$X'' + P(z)X' + Q_k(z)X = 0, \quad (1)$$

where

$$P(z) = \frac{\ddot{z}}{(\dot{z})^2} = \frac{2z}{2z^2 - \eta + 1} + \frac{2z}{2z^2 - \eta - 1},$$

$$Q_k(z) = -\frac{b_k}{(\dot{z})^2} = \frac{4 \left[ -6z^2 + c_k(3 + 4z(\sqrt{3} + 3z) - 3\eta) + 3\eta \right]}{3 \left[ (\eta - 2z^2)^2 - 1 \right]}.$$

# Variational equations

Set  $\eta = 1$  and change independent variable

$$X = w \exp \left[ -\frac{1}{2} \int^z P(v) dv \right], \quad (2)$$

which convert equations (1) into its reduced form

$$w'' = r_k(z)w, \quad r_k(z) = \frac{1}{2}P'(z) + \frac{1}{4}P(z)^2 - Q_k(z).$$

$$r_k(z) = \frac{3/4}{z^2} - \frac{3/16}{(z-1)^2} - \frac{3/16}{(z+1)^2} + \frac{4c_k}{\sqrt{3z}} + \frac{39 - 32c_k(3 + \sqrt{3z})}{24(z^2 - 1)}$$

$r_k$  is a symmetric function of  $\lambda_1$  and  $\lambda_2$  as

$$c_k = \frac{\varepsilon_k \lambda - 2}{2\sigma}, \quad \text{where } \sigma := \lambda_1 \lambda_2 - 1, \quad \lambda := \lambda_1 + \lambda_2.$$

# Main steps

Differential Galois group  $\mathcal{G}_k$  of  $w'' = r_k(z)w$  is algebraic subgroup of  $\mathrm{SL}(2, \mathbb{C})$ .

## Lemma (A)

If  $\mathcal{G}$  is an algebraic subgroup of  $\mathrm{SL}(2, \mathbb{C})$ , then (up to conjugation):

1

$$\mathcal{G} \subset \begin{bmatrix} a & b \\ 0 & a^{-1} \end{bmatrix}$$

2

$$\mathcal{G} \subset \begin{bmatrix} a & 0 \\ 0 & a^{-1} \end{bmatrix} \cup \begin{bmatrix} 0 & b \\ -b^{-1} & 0 \end{bmatrix}$$

3  $\mathcal{G}$  is classical finite group (tetrahedral, octahedral or icosahedral);

4  $\mathcal{G} = \mathrm{SL}(2, \mathbb{C})$

# Logarithmic term

Equations  $w'' = r_k(z)w$  have four themed singular point  $\{0, \pm 1, \infty\}$  (i.e., they are Heun equations). The differences of exponents at these points are:

$$\Delta_0 = 2, \quad \Delta_{\pm 1} = \frac{1}{2}, \quad \Delta_\infty = \delta_k,$$

where

$$\delta_1 = \sqrt{9 + 8\frac{2 + \lambda}{\sigma}}, \quad \delta_2 = \sqrt{9 + 8\frac{2 - \lambda}{\sigma}}.$$

Solutions near  $z = 0$ :

$$w_1(z) = z^{3/2}f(z), \quad w_2(z) = gw_1(z) \ln z + z^{-1/2}h(z),$$

where  $f(z)$  and  $h(z)$  are holomorphic at  $z = 0$  and  $f(0) \neq 0$ .

# Logarithmic term

$$w_1(z) = z^{3/2}f(z), \quad w_2(z) = gw_1(z) \ln z + z^{-1/2}h(z),$$

where

$$g = \frac{1}{6} \left( 8c_k^2 - 6c_k + 3 \right). \quad (3)$$

so,  $g > 0$  for arbitrary  $c_k \in \mathbb{R}$ . Monodromy around  $z = 0$

$$M_0 := \begin{bmatrix} -1 & -2\pi i \\ 0 & -1 \end{bmatrix}.$$

This excludes case 2 and 3 from Lemma A **for both variational equations.**



## Elimination of reducible case.

If the first case of Lemma A occurs then the considered variational equation has a solution of the form

$$w = P(z) \exp \left[ \int^z \omega(s) ds \right], \quad P \in \mathbb{C}[z], \quad \omega(z) \in \mathbb{C}(z).$$

Analysis around singularities gives restriction  $\delta_1, \delta_2 \in \mathbb{Z}$ .

Physical restrictions on  $(\lambda, \sigma)$ , limits  $\delta_2 \in \{0, 1, 2\}$  but for these case solution of prescribed form does not exist.

**Conclusion:**  $\mathcal{G}_k = \text{SL}(2, \mathbb{C})$ .

Maciejewski A., J. and M. Przybylska, *Non-integrability of multibody chain in circular orbit*, submitted for publication.

# Outline

---

- 1 Open chains dynamics
- 2 Constrained systems on a sphere (not finished)
- 3 Anisotropic Kepler problem

# A dumbbell on a sphere

Consider two points  $(m_1, \mathbf{r}_1)$  and  $(m_2, \mathbf{r}_2)$  with  $\mathbf{r}_i \in \mathbb{S}^2$ , and holonomic constrain  $\mathbf{r}_1 \cdot \mathbf{r}_2 = c_1$ .

This system is equivalent to a (flat) rigid body with a fixed point.

Add a third point  $(m_3, \mathbf{r}_3)$  with constrain  $\mathbf{r}_2 \cdot \mathbf{r}_3 = c_2$ .

This system is equivalent to a rigid body with a fixed point and one point moving along a circle fixed in the body.

# Outline

---

- 1 Open chains dynamics
- 2 Constrained systems on a sphere (not finished)
- 3 Anisotropic Kepler problem**

# Anisotropic Kepler problems

$$H = \frac{1}{2}(p_x^2 + p_y^2) - \frac{1}{\sqrt{x^2 + \mu y^2}}$$

- Introduced in <sup>1</sup>
- Investigated in many papers e.g. <sup>2 3</sup>
- non-integrability proofs using Morales-Ramis theory in <sup>4</sup>

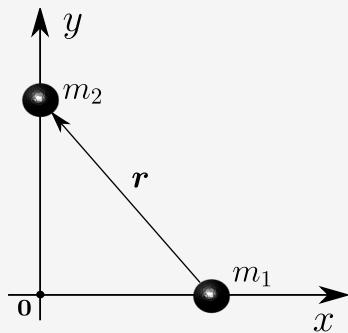
<sup>1</sup>Gutzwiller M.C., Bernoulli sequences and trajectories in the anisotropic Kepler problem *J. Math. Phys* 18(4):806–823, 1977.

<sup>2</sup>Casasayas J., Llibre J, Qualitative Analysis of the Anisotropic Kepler Problem, *Memoirs of Amer. Math. Soc.* 52, no. 312, 1984.

<sup>3</sup>Devaney R. L., Blowing up Singularities in Classical Mechanical Systems, *Amer. Math. Monthly*, 89:535–552, 1982.

<sup>4</sup>Arribas M., Elipe A., Riaguas, A, Non-integrability of anisotropic quasi-homogeneous Hamiltonian systems, *Mech. Res. Comm.*, 30(3):209–216, 2003.

# Relation to anisotropic Kepler problem



$$H = \frac{p_x^2}{2m_1} + \frac{p_y^2}{2m_2} - \frac{a}{\sqrt{x^2 + y^2}}.$$

after rescaling

$$p_x = \sqrt{m_1}p_1, \quad p_y = \sqrt{m_2}p_2,$$

$$x = \frac{1}{\sqrt{m_1}}q_1, \quad y = \frac{1}{\sqrt{m_2}}q_2$$

$$\tilde{H} = \frac{1}{2}(p_1^2 + p_2^2) + \frac{a}{\sqrt{\mu_1 q_1^2 + \mu_2 q_2^2}},$$

$$\mu_1 = 1/\sqrt{m_1}, \quad \mu_2 = 1/\sqrt{m_2}.$$

# Generalised anisotropic Kepler problem

$$H = \frac{1}{2} (p_1^2 + p_2^2) - (\mu_1 q_1^2 + \mu_2 q_2^2)^{-n}, \quad 2n \in \mathbb{Z},$$

## Theorem

*Hamiltonian system generated by  $H$  is integrable in the Liouville sense with meromorphic first integrals in three cases:*

- 1 radial case when  $\mu_1 = \mu_2$ ,*
- 2 uncoupled linear oscillators case when  $n = -1$ ,*
- 3 degree  $k = -2$  potential when  $n = 1$ .*

*In the remaining cases the system is not integrable.*

# Difficult case

## Proposition

*Hamiltonian system given by*

$$\tilde{H} = \frac{1}{2} (p_1^2 + p_2^2) - (q_1^2 - q_2^2)^{-3/2}, \quad (4)$$

*is not integrable.*



# Integrability of homogeneous Hamiltonian equations

Integrability of Hamiltonian systems given by

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + V(\mathbf{q}), \quad (\mathbf{q}, \mathbf{p}) \in \mathbb{C}^{2n},$$

$V$  — homogeneous of degree  $k$

# Particular solutions

## Definition

Darboux point  $\mathbf{d} \in \mathbb{C}^n$  is a non-zero solution of

$$V'(\mathbf{d}) = \mathbf{d}$$

Particular solution

$$\mathbf{q}(t) = \varphi(t)\mathbf{d}, \quad \mathbf{p}(t) = \dot{\varphi}(t)\mathbf{d} \quad \text{provided} \quad \ddot{\varphi} = -\varphi^{k-1}.$$

On the energy level:

$$H(\varphi(t)\mathbf{d}, \dot{\varphi}(t)\mathbf{d}) = e \in \mathbb{C}^*,$$

hyperelliptic curve

$$\dot{\varphi}^2 = \frac{2}{k} \left( \varepsilon - \varphi^k \right), \quad \varepsilon = ke \in \mathbb{C}^*.$$

# Variational equations

$$\ddot{\mathbf{x}} = -\varphi(t)^{k-2}V''(\mathbf{d})\mathbf{x},$$

where  $V''(\mathbf{d})$  is the Hessian of  $V$  calculated at  $\mathbf{d}$ . If  $V''(\mathbf{d})$  is diagonalisable

$$\ddot{\eta}_i = \lambda_i \varphi(t)^{k-2} \eta_i, \quad i = 1, \dots, n,$$

where  $\lambda_i$  for  $i = 1, \dots, n$  are eigenvalues of  $V''$ .

By homogeneity of  $V$ ,  $\lambda_n = k - 1$ .

## Other Morales-Ramis Theorem

If the Hamiltonian system with homogeneous potential is meromorphically integrable, then each  $(k, \lambda_i)$  belong to the following list:

1.  $\left(k, p + \frac{k}{2}p(p-1)\right),$
2.  $\left(k, \frac{1}{2} \left[ \frac{k-1}{k} + p(p+1)k \right] \right),$
3.  $(2, \text{arbitrary}),$
4.  $(-2, \text{arbitrary}),$
5.  $\left(3, -\frac{1}{24} + \frac{1}{6}(1+3p)^2\right),$
6.  $\left(3, -\frac{1}{24} + \frac{3}{32}(1+4p)^2\right),$
7.  $\left(3, -\frac{1}{24} + \frac{3}{50}(1+5p)^2\right),$
8.  $\left(3, -\frac{1}{24} + \frac{3}{50}(2+5p)^2\right),$

$$\begin{array}{ll}
9. & \left(4, -\frac{1}{8} + \frac{2}{9} (1 + 3p)^2\right), & 10. & \left(5, -\frac{9}{40} + \frac{5}{18} (1 + 3p)^2\right), \\
11. & \left(5, -\frac{9}{40} + \frac{1}{10} (2 + 5p)^2\right), & 12. & \left(-3, \frac{25}{24} - \frac{1}{6} (1 + 3p)^2\right), \\
13. & \left(-3, \frac{25}{24} - \frac{3}{32} (1 + 4p)^2\right), & 14. & \left(-3, \frac{25}{24} - \frac{3}{50} (1 + 5p)^2\right), \\
15. & \left(-3, \frac{25}{24} - \frac{3}{50} (2 + 5p)^2\right), & 16. & \left(-4, \frac{9}{8} - \frac{2}{9} (1 + 3p)^2\right), \\
17. & \left(-5, \frac{49}{40} - \frac{5}{18} (1 + 3p)^2\right), & 18. & \left(-5, \frac{49}{40} - \frac{1}{10} (2 + 5p)^2\right),
\end{array}$$

## Easy part

Potential  $V = -(\mu_1 q_1^2 + \mu_2 q_2^2)^{-n}$  has two Darboux points

$$\mathbf{d}_1 = \left(0, (2n)^{\frac{1}{2+2n}} \mu_2^{-\frac{n}{2+2n}}\right), \quad \mathbf{d}_2 = \left((2n)^{\frac{1}{2+2n}} \mu_1^{-\frac{n}{2+2n}}, 0\right).$$

Hessians of potential calculated at these points are diagonal matrices

$$V''(\mathbf{d}_1) = \text{diag}\left(\frac{1}{\mu}, -2n - 1\right), \quad V''(\mathbf{d}_2) = \text{diag}(-2n - 1, \mu),$$

where  $\mu := \mu_2/\mu_1$ . **If the system is integrable then pairs  $(-2n, \mu)$  and  $(-2n, 1/\mu)$  belong to the Morales-Ramis table.**

Case  $\mu = -1, n = 3/2$  in item 1, with  $p = 2$ .

# Variational Equations $VE_i$

## ■ System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m, \quad t \in \mathbb{C}. \quad (\text{N})$$

# Variational Equations $VE_i$

- System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m, \quad t \in \mathbb{C}. \quad (\text{N})$$

- Particular solution:  $\boldsymbol{\varphi}(t)$ .



# Variational Equations $VE_i$

- System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m, \quad t \in \mathbb{C}. \quad (\text{N})$$

- Particular solution:  $\boldsymbol{\varphi}(t)$ .

- Expansion:  $\mathbf{x} = \boldsymbol{\varphi}(t) + \varepsilon\mathbf{x}_1 + \frac{1}{2!}\varepsilon^2\mathbf{x}_2 + \dots$

# Variational Equations $VE_i$

- System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m, \quad t \in \mathbb{C}. \quad (\text{N})$$

- Particular solution:  $\boldsymbol{\varphi}(t)$ .

- Expansion:  $\mathbf{x} = \boldsymbol{\varphi}(t) + \varepsilon\mathbf{x}_1 + \frac{1}{2!}\varepsilon^2\mathbf{x}_2 + \dots$

- Variational equation:

$$\frac{d}{dt}\mathbf{x}_1 = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\boldsymbol{\varphi}(t)) \cdot \mathbf{x}_1, \quad \mathbf{x}_1 \in \mathbb{C}^m, \quad (\text{VE}_1)$$

$$\frac{d}{dt}\mathbf{x}_i = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\boldsymbol{\varphi}(t)) \cdot \mathbf{x}_i + \mathbf{f}_i(\mathbf{x}_1, \dots, \mathbf{x}_{i-1}), \quad (\text{VE}_i)$$

with  $i = 2, 3, \dots$

# Variational Equations $VE_i$

- System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m, \quad t \in \mathbb{C}. \quad (\text{N})$$

- Particular solution:  $\boldsymbol{\varphi}(t)$ .

- Expansion:  $\mathbf{x} = \boldsymbol{\varphi}(t) + \varepsilon\mathbf{x}_1 + \frac{1}{2!}\varepsilon^2\mathbf{x}_2 + \dots$

- Variational equation:

$$\frac{d}{dt}\mathbf{x}_1 = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\boldsymbol{\varphi}(t)) \cdot \mathbf{x}_1, \quad \mathbf{x}_1 \in \mathbb{C}^m, \quad (\text{VE}_1)$$

$$\frac{d}{dt}\mathbf{x}_i = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\boldsymbol{\varphi}(t)) \cdot \mathbf{x}_i + \mathbf{f}_i(\mathbf{x}_1, \dots, \mathbf{x}_{i-1}), \quad (\text{VE}_i)$$

with  $i = 2, 3, \dots$

- Differential Galois Group:  $\text{Gal}(\text{VE}_i) = \text{Gal}(L_i/K)$ .

# Non-Hamiltonian Systems

System

$$\frac{d}{dt}\mathbf{x} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{C}^m. \quad (\text{N})$$

Theorem of M. Ayoul and T. Zung (2010)

## Theorem

If the system (N) is  $B$ -integrable, then for each  $i \in \mathbb{N}$  group  $\text{Gal}(\text{VE}_i)$  is virtually Abelian.

# Hamiltonian Systems

- Hamiltonian function:  $H = H(\mathbf{q}, \mathbf{p}), \mathbf{q}, \mathbf{p} \in \mathbb{C}^n$ .

# Hamiltonian Systems

- Hamiltonian function:  $H = H(\mathbf{q}, \mathbf{p}), \mathbf{q}, \mathbf{p} \in \mathbb{C}^n$ .
- Equations:

$$\begin{cases} \frac{d}{dt}q_i = \frac{\partial H}{\partial p_i}, \\ \frac{d}{dt}p_i = -\frac{\partial H}{\partial q_i}, \end{cases} \quad i = 1, \dots, n. \quad (\text{H})$$

# Hamiltonian Systems

- Hamiltonian function:  $H = H(\mathbf{q}, \mathbf{p}), \mathbf{q}, \mathbf{p} \in \mathbb{C}^n$ .
- Equations:

$$\begin{cases} \frac{d}{dt}q_i = \frac{\partial H}{\partial p_i}, \\ \frac{d}{dt}p_i = -\frac{\partial H}{\partial q_i}, \end{cases} \quad i = 1, \dots, n. \quad (\text{H})$$

- Theorem of J. J. Morales, J.-P. Ramis, and C. Simó (2007)

## Theorem

If the system (H) is integrable in the Liouville sense, then for each  $i \in \mathbb{N}$  group  $\text{Gal}(\text{VE}_i)$  is virtually Abelian.

# Natural Hamiltonian Systems

- Hamiltonian function:

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + V(\mathbf{q}).$$



# Natural Hamiltonian Systems

- Hamiltonian function:

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + V(\mathbf{q}).$$

- Equations:

$$\begin{cases} \frac{d}{dt}q_i = p_i, \\ \frac{d}{dt}p_i = -\frac{\partial V}{\partial q_i}, \end{cases} \quad i = 1, \dots, n. \quad (\text{H})$$

or just

$$\ddot{\mathbf{q}} = \mathbf{F}(\mathbf{q}), \quad \text{where} \quad \mathbf{F}(\mathbf{q}) = -V'(\mathbf{q}).$$

# Natural Hamiltonian Systems

---

# Natural Hamiltonian Systems

- If  $V(\mathbf{q})$  is homogeneous of degree  $k \in \mathbb{Z}^*$ , then

$$\mathbf{q}(t) = \varphi(t)\mathbf{d}, \quad \dot{\mathbf{q}}(t) = \dot{\varphi}(t)\mathbf{d},$$

where

$$V'(\mathbf{d}) = \mathbf{d}, \quad \text{and} \quad \ddot{\varphi} = -\varphi^{k-1}.$$

# Natural Hamiltonian Systems

■  $VE_1$ :

$$\ddot{\mathbf{x}} = -\varphi(t)^{k-2} V''(\mathbf{d}) \cdot \mathbf{x}.$$

# Natural Hamiltonian Systems

- $VE_1$ :

$$\ddot{\mathbf{x}} = -\varphi(t)^{k-2} V''(\mathbf{d}) \cdot \mathbf{x}.$$

- If  $V''(\mathbf{d})$  is diagonalisable, then  $V''(\mathbf{d}) = \text{diag}(\lambda_1, \dots, \lambda_n)$ , and

$$\ddot{x}_i = -\lambda_i \varphi(t)^{k-2} x_i, \quad i = 1, \dots, n.$$

# Natural Hamiltonian Systems

- $VE_1$ :

$$\ddot{\mathbf{x}} = -\varphi(t)^{k-2} V''(\mathbf{d}) \cdot \mathbf{x}.$$

- If  $V''(\mathbf{d})$  is diagonalisable, then  $V''(\mathbf{d}) = \text{diag}(\lambda_1, \dots, \lambda_n)$ ,  
and

$$\ddot{x}_i = -\lambda_i \varphi(t)^{k-2} x_i, \quad i = 1, \dots, n.$$

- Morales-Ramis Theorem

# VE<sub>p</sub> and Taylor Expansion

$$\ddot{\mathbf{x}}_1 = -\varphi(t)^{k-2}V''(\mathbf{d}) \cdot \mathbf{x}_1, \quad (\text{VE}_1)$$

$$\ddot{\mathbf{x}}_2 = -\varphi(t)^{k-2}V''(\mathbf{d}) \cdot \mathbf{x}_2 - \varphi(t)^{k-3}V^{(3)}(\mathbf{d}) \cdot (\mathbf{x}_1, \mathbf{x}_1), \quad (\text{VE}_2)$$

$$\begin{aligned} \ddot{\mathbf{x}}_3 = & -\varphi(t)^{k-2}V''(\mathbf{d}) \cdot \mathbf{x}_3 - \varphi(t)^{k-3}V^{(3)}(\mathbf{d}) \cdot (\mathbf{x}_1, \mathbf{x}_2) - \\ & - \varphi(t)^{k-4}V^{(4)}(\mathbf{d}) \cdot (\mathbf{x}_1, \mathbf{x}_1, \mathbf{x}_1). \end{aligned} \quad (\text{VE}_3)$$

$$K = \mathbb{C}(\varphi, \dot{\varphi})$$

## VE<sub>2</sub> splitting

If  $V''(\mathbf{d}) = \text{diag}(\lambda_1, \dots, \lambda_n)$  then we select following subsystems of VE<sub>2</sub>

$$\left. \begin{aligned} \ddot{x} &= -\lambda_\alpha \varphi(t)^{k-2} x, \\ \ddot{y} &= -\lambda_\gamma \varphi(t)^{k-2} y + \varphi(t)^{k-3} \theta_{\alpha,\alpha}^\gamma x^2, \end{aligned} \right\} \quad (\text{VE}_{2,\alpha}^\gamma)$$

and

$$\left. \begin{aligned} \ddot{x} &= -\lambda_\alpha \varphi(t)^{k-2} x, \\ \ddot{y} &= -\lambda_\beta \varphi(t)^{k-2} y, \\ \ddot{z} &= -\lambda_\gamma \varphi(t)^{k-2} z + 2\varphi(t)^{k-3} \theta_{\alpha,\beta}^\gamma xy. \end{aligned} \right\} \quad (\text{EX}_{2,(\alpha,\beta)}^\gamma)$$



- 1 Duval G. and Maciejewski A. J., 2014, Integrability of Hamiltonian systems with homogeneous potentials of degree  $\pm 2$ . An application of higher order variational equations, *Discrete Contin. Dyn. Syst.* , 34(11):4589–4615.
- 2 Duval G. and Maciejewski A. J., 2015, Integrability of potentials of degree  $k \neq \pm 2$ . Second order variational equations between Kolchin solvability and abelianity, *Discrete Contin. Dyn. Syst.* , 35(5):1969–2009.

# Rationalization

$$\left. \begin{aligned} x'' &= r_\alpha(z)x, \\ y'' &= r_\gamma(z)y + \omega(z)x^2, \end{aligned} \right\} \quad (\text{VE}_{2,\alpha}^\gamma)$$

where

$$\omega(z) = z^{-\frac{3}{2} - \frac{1}{2k}} (1-z)^{-\frac{5}{4}}$$

In our case  $k = -3$ ,  $\lambda_\alpha = -1$ ,  $\lambda_\gamma = -4$ . Solutions of  $\text{VE}_1$ :

$$x_1 = z^{1/3}(1-z)^{3/4}, \quad I_\alpha = \int \frac{1}{x_1^2} = 2 \frac{z^{1/3}}{\sqrt{1-z}} + \frac{1}{3} B(z, 1/3, 1/2)$$

$$y_1 = z^{2/3}(1-z)^{3/4}, \quad I_\gamma = \frac{5z-3}{z^{1/3}\sqrt{1-z}} - \frac{5}{6} B(z, 2/3, 1/2)$$

# Integrals

$$\Phi = \int \omega(z) y_1 x_1^2 = z - \frac{1}{2} z^2$$

but

$$\Phi_\gamma := \int \omega(z) y_2 x_1^2$$

is very complicated.

However we can consider also

$$\Psi_\gamma := \int \Phi I'_\gamma = \frac{z^{2/3}}{\sqrt{1-z}} + \frac{1}{3} B(z, 2/3, 1/2)$$

# Key point

Necessary condition for integrability: there exists Ostrowski relation

$$d_\alpha I_\alpha + d_\gamma I_\gamma \in K = \mathbb{C}(z)[\omega]$$

with  $(d_\alpha, d_\gamma) \in \mathbb{C}^2 \setminus \{(0,0)\}$ . But it does not exist!. (Theorem 5.3 in ref. 2)