

## On derivations of the ternary Malcev algebra $M_8$

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Ternary Malcev algebras are a particular case of  $n$ -ary Malcev algebras, first defined in [3], and these naturally arise from the classification of  $n$ -ary vector cross product algebras [1]. Indeed, the classification theorem for the latter asserts that, in the case  $n = 2$ , the only possible algebras are the simple 3-dimensional Lie algebra  $sl(2)$  and the simple 7-dimensional Malcev algebra  $C_7$ ; in the case  $n \geq 3$ , those are the simple  $(n + 1)$ -dimensional  $n$ -Lie algebras (which, in turn, are a natural generalization of Lie algebras to the case of an  $n$ -ary multiplication [2], and nowadays called *Filippov algebras*) with vector cross product, being analogues of  $sl(2)$ , and also some exclusive ternary algebras arising on composition algebras.

It has been proved [3] that the latter are ternary central simple Malcev algebras, which are not 3-Lie algebras if the characteristic of the ground field is different from 2 and 3 (more generally, the result states that every  $n$ -ary vector cross product algebra is an  $n$ -ary central simple Malcev algebra).

The class of  $n$ -ary Malcev algebras has also the following interesting properties:

1. It is an extension of the class of  $n$ -Lie algebras, *i.e.*, every  $n$ -Lie algebra is an  $n$ -ary Malcev algebra (generalizing the fact that every Lie algebra is a Malcev algebra);
2. Fixing a component in the multiplication (*i.e.*, defining a new reduced operation on the vector space  $A$  of the  $n$ -ary Malcev algebra by the rule  $[x_1, \dots, x_{n-1}]_a = [a, x_1, \dots, x_{n-1}]$ ), we obtain an  $(n - 1)$ -ary Malcev algebra.

By an  $n$ -ary Jacobian, we mean the following function defined on an

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$n$ -ary algebra:

$$J(x_1, \dots, x_n; y_2, \dots, y_n) = [[x_1, \dots, x_n], y_2, \dots, y_n] - \sum_{i=1}^n [x_1, \dots, [x_i, y_2, \dots, y_n], \dots, x_n].$$

An  $n$ -ary Malcev algebra ( $n \geq 3$ ) is an  $\Omega$ -algebra  $L$  with one anticommutative  $n$ -ary operation  $[x_1, \dots, x_n]$  satisfying the identity

$$-J(zR_x, x_2, \dots, x_n; y_2, \dots, y_n) = J(z, x_2, \dots, x_n; y_2, \dots, y_n)R_x,$$

where  $R_x = R_{x_2, \dots, x_n}$  is the operator of right multiplication.

Henceforth, we assume that  $\Phi$  is a field of characteristic not equal to 2, 3 and denote by  $A$  a composition algebra over  $\Phi$  with an involution  $- : a \mapsto \bar{a}$  and nonsingular symmetric bilinear form  $\langle x, y \rangle = \frac{1}{2}(x\bar{y} + y\bar{x})$ . If  $A$  is equipped with a ternary multiplication  $[\cdot, \cdot, \cdot]$  by the rule

$$[x, y, z] = x\bar{y}z - \langle y, z \rangle x + \langle x, z \rangle y - \langle x, y \rangle z,$$

then  $A$  becomes a ternary Malcev algebra which will be denoted by  $M(A)$ . If  $\dim A = 8$  then  $M(A)$  is not a 3-Lie algebra and we denote it by  $M_8$ .

Let  $\mathcal{R}$  be the vector space generated by the right multiplications of  $M_8$ . Let  $Ass(\mathcal{R})$  and  $Lie(\mathcal{R})$  denote, respectively, the associative and the Lie algebra generated by  $\mathcal{R}$ . Let  $Der(M_8)$  be the derivation algebra of  $M_8$ . Recall that a derivation is called *inner* if it belongs to the Lie algebra  $Lie(\mathcal{R})$  of transformations.

- Theorem 1.** 1.  $Ass(\mathcal{R}) = M_{8,8}(\Phi) = \langle \mathcal{R}^2 \rangle$ ;  
 2.  $Lie(\mathcal{R}) \cong D_4$  and  $Lie(\mathcal{R}) = \mathcal{R}$  as vector spaces;  
 3.  $Der(M_8) \cong B_3$ .

**Theorem 2.** All derivations of  $M_8$  are inner.

In the case of Malcev algebras we know that the operators of the type  $[R_x, R_y] + R_{xy}$  are inner derivations.

**Theorem 3.** Let  $M(A)$  be a ternary Malcev algebra. For any  $x, y, z \in A$

$$[R_{z,x}, R_{z,y}] + R_{z,[x,z,y]} \in Der(M(A)).$$

Let  $A$  be an  $n$ -ary anticommutative algebra with multiplication  $[\cdot, \dots, \cdot]$ . Every operator  $D : A \rightarrow A$  such that

$$[D, R_a] \in Lie(\mathcal{R}), \text{ for all } R_a \in Lie(\mathcal{R}),$$

is said to be a *quasi-derivation* of  $A$ . The set of all quasi-derivations of the algebra  $A$  we denote by  $QDer(A)$ .

**Theorem 4.**  $QDer(M_8) = \langle Id \rangle_{\Phi} \oplus Lie(\mathcal{R})$ .

In the proofs of all these results we use some symmetries of the canonical basis of a composition algebra.

## References

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